Adaptive robotised post-weld treatment to enable sustainable designs

Results from FFI-MIDWEST presented by:

Joakim Hedegård, Swerim

Erik Åstrand, Volvo CE

Alexander von Essen, Winteria

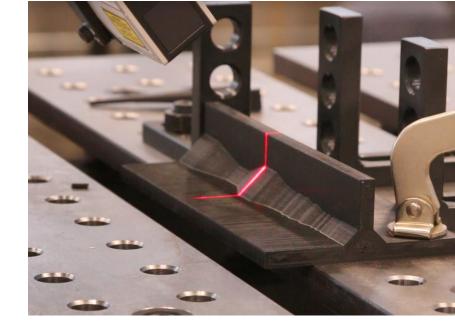
Images also from Kurt Broeckx, HIAB, Christian Thune, Toyota MH, Leif Bäckman & Mikael Reinberth, SSAB

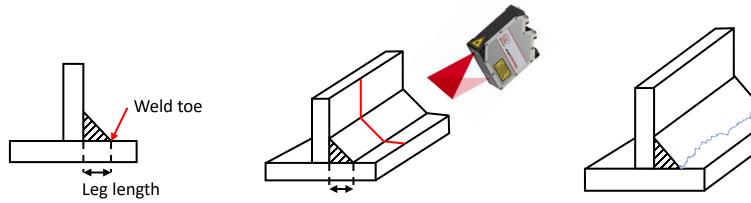


FFI-MIDWEST

The idea with a mechanised post-weld-treatment in robot with an adaptive robot path:

Weld a component, scan the weld and arrange an adapted robot path along the weld toe, treat it with a fatigue-improving technique.





- Laser scan deliver info on weld-toe position along the weld
- Calculations based on this gives an adapted robot path, that follows the weld toe line very accurately







$\label{eq:model} MIDWEST - {\tt an FFI project enabling robotization of important weld improvement methods}$

• Scope and objective

Mechanised post-weld treatment in welding robot: weld a component, create an adapted path along the weld and treat to reduce stress and increase fatigue life.

• Partners

Swerim, KTH, Chalmers, Volvo CE, HIAB, Gestamp, ToyotaMH, ABB, SSAB, Winteria, Weld-Hit, HiFIT. And Robotdalen as subcontractor to Swerim.

Results

Adaptive treatment in robot (HFMI + TIG) very successful

Adaptive robotic grinding: proof of concept

Very good fatigue results

New product to come – Automated PWT path adjustment

• Financing

VINNOVA FFI-sustainable production 7.8MSEK whereof 3.9MSEK from VINNOVA

• Project duration & lead

2020-11-13 – 2023-12-31 Joakim Wahlsten & Joakim Hedegård, Swerim





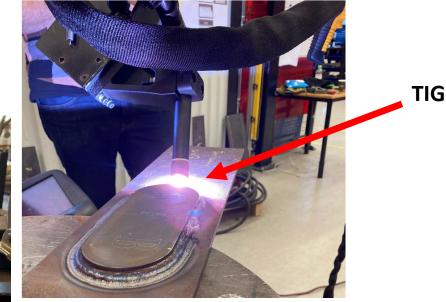


Post weld treatment of welds in different shapes

Fatigue could initiate on edges or irregularity in base material instead of in the weld toe.

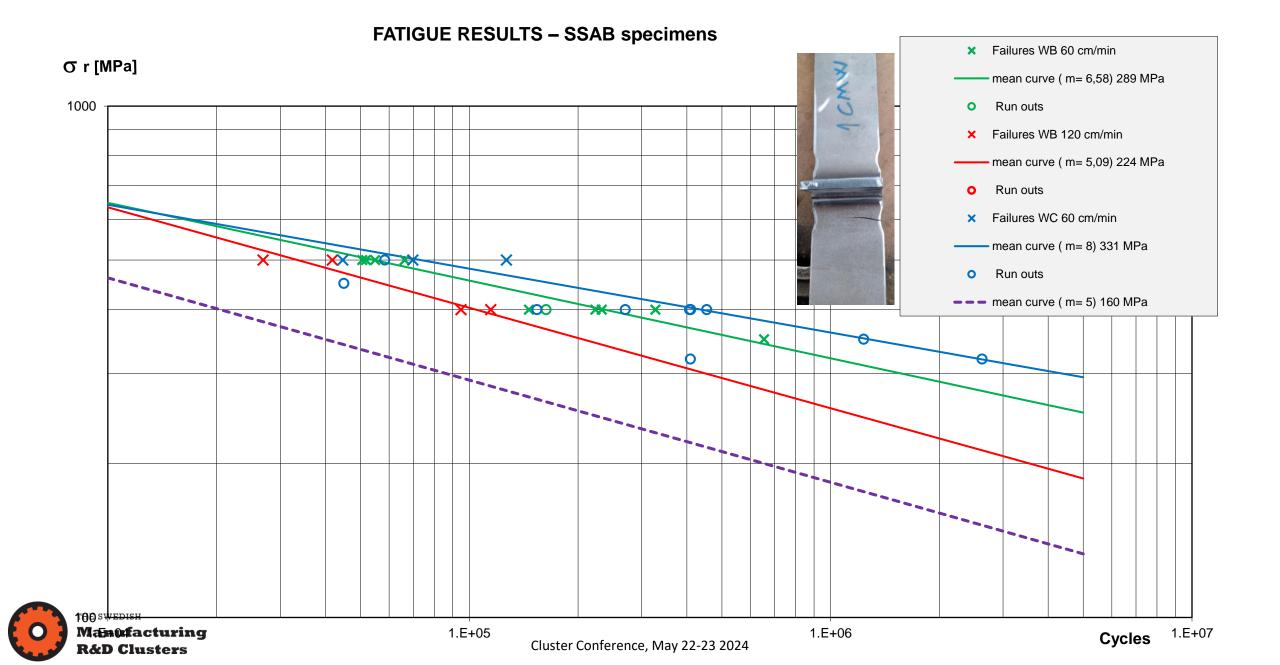






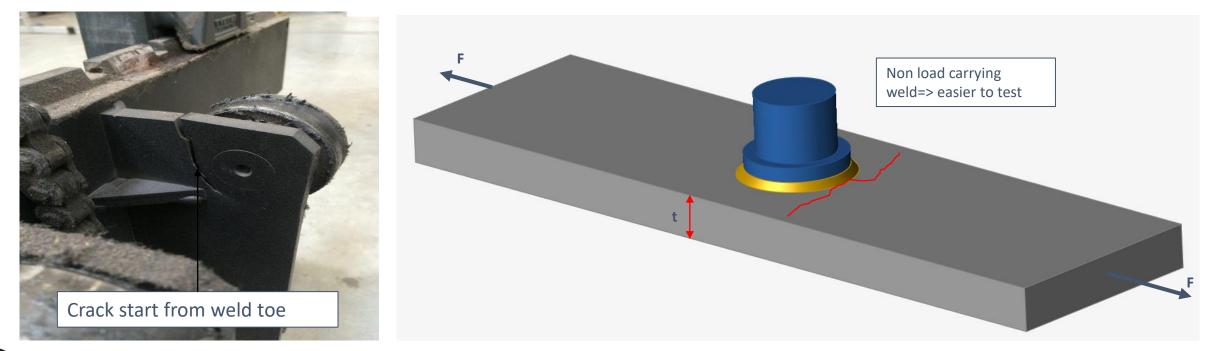


Cluster Conference, May 22-23 2024

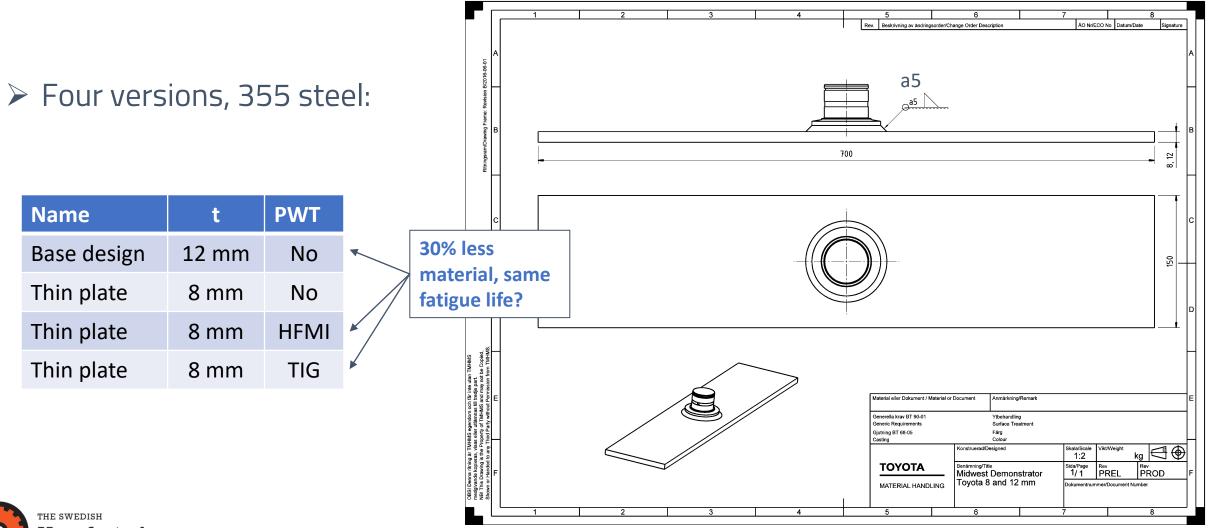


Axle on plate

- > Very common joint type
- > How much thinner can the plate be made, with additional PWT (equal life)?







Manufacturing R&D Clusters

Welding by robot



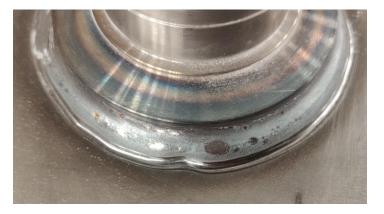
PWT by robot











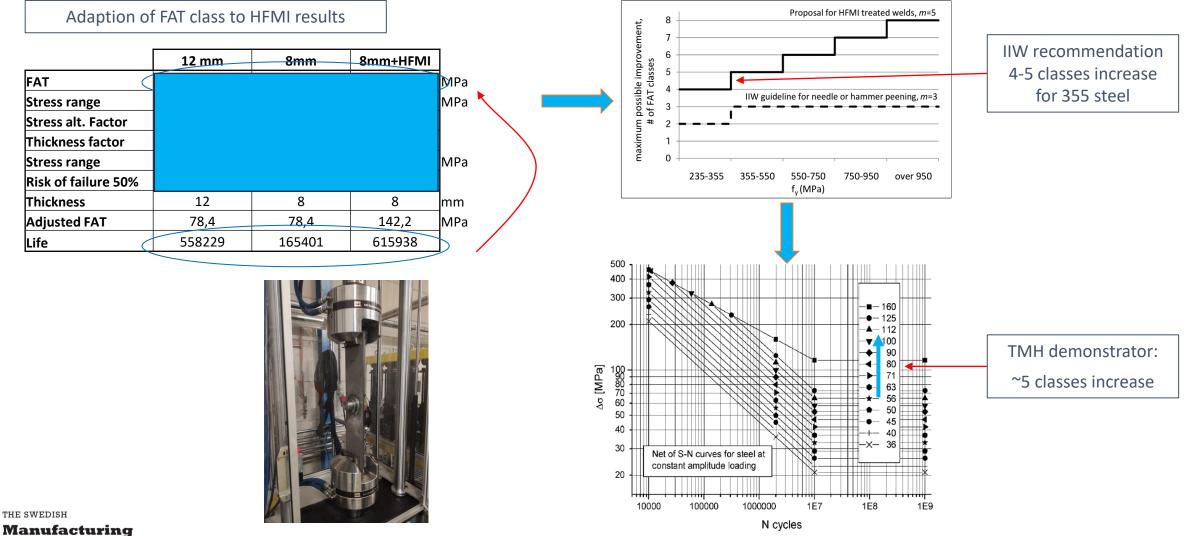


As welded







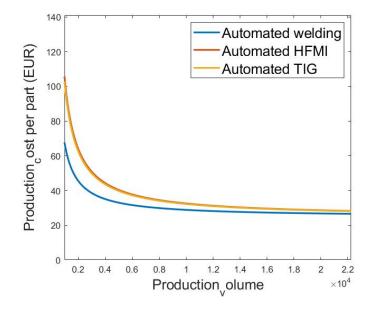


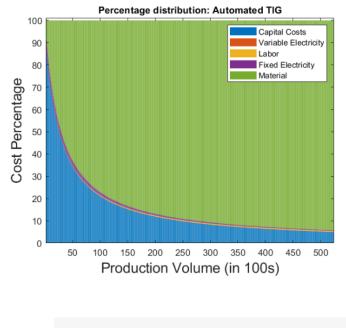
Manufacturing R&D Clusters

- > The developed robotized PWT works very well
- > A 12 mm plate can be replaced with an 8 mm plate for regular steel
- > Weight reduction 30% with equal life
- > More spread in these fatigue results for HFMI and TIG
- > TIG gives higher life but more heat deformation
- > Further gain possible with HS-steel, lower design stress range and optimised PWT

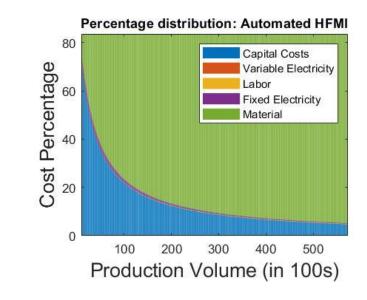


MIDWEST - LCC for Toyota demonstrator







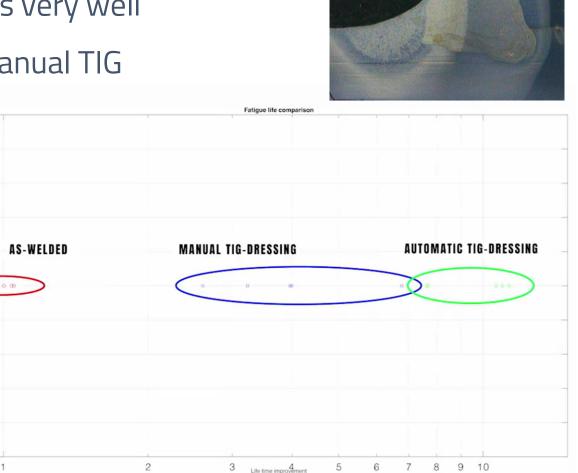




MIDWEST Volvo+HIAB demonstrator

- > The developed robotized TIG-process works very well
- > The process windows are larger than for manual TIG
- > Significantly increased fatigue life







MIDWEST Volvo+HIAB demonstrator





Conclusions

- > The developed robotized PWT with adaptive path works very well for TIG & HFMI
- > Weight reductions of 30% or more are possible
- > Substantially increased fatigue life for welded designs treated with robotized PWT
- > Further gain possible with HS-steel, and optimised PWT
- > New product to come Automated PWT path adjustment
- The new possibilities and other PWT methods are to be further explored in a MIDWEST-2 that will be applied for.
 - -Are you interested in participating? Contact:

Joakim.hedegard@swerim.se & Joakim.wahlsten@swerim.se



- Mekaniserad efterbehandling av svetsade konstruktioner för fordons- och lastapplikationer Open report Publik rapport

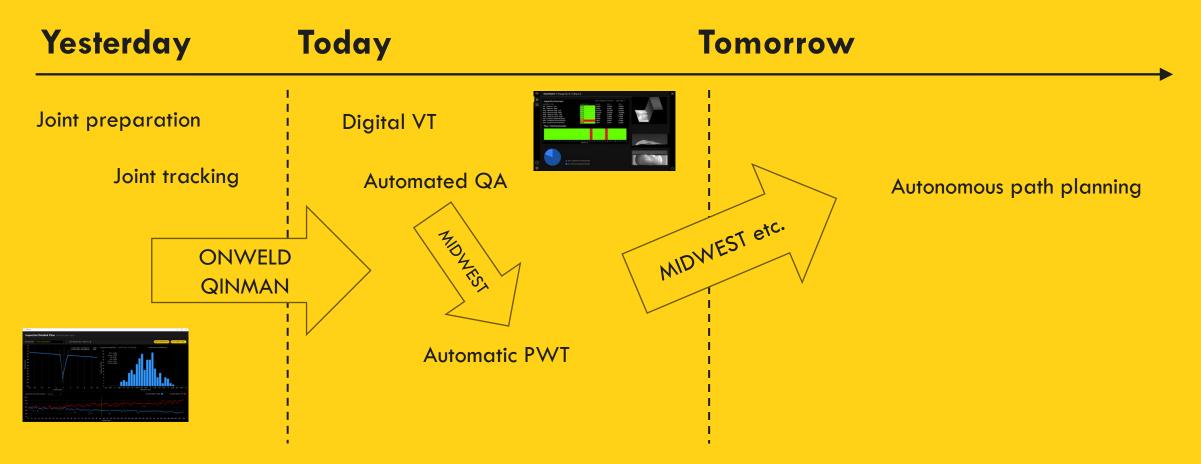


hors: Joakim Wahlsten, Joakim Hedegård, David Franklin, Zuheir Barsoum, Kaushik Iyer, Yuki Banno, Gustav Hultgren, Erik Hellström, Kurt Broeckx, Lars Rydahl, Robin Kadi, Erik Åstrand, Anton Johansson, Michael Roll, Mikael Reinberth, Torbjörn Narström, Leif Bäckman, Christian Thune, Angelica Djurberg, Rolf Andersson, Michael Neher, Armar Björnsson, Eric Lindgren, Martin Engman, Alexander von Essen 2024-01-31



Automatic PWT and Beyond

Commercialization of the research results





Autonomous path planning

Possible applications

Automated treatment of the joint or selected part of the joint

Automatic repair

Self-adjusting production cells

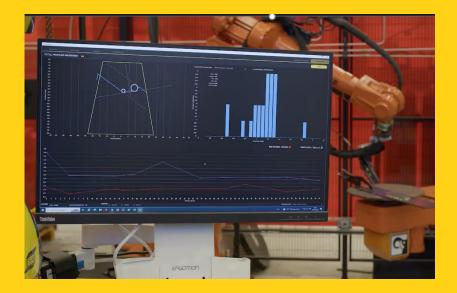
Full 3D joint tracking of complex geometries

Weld sequence planning in multi-layer welds including WAAM



Automatic PWT module ready

Working module for ABB robots.





Thank you for the attention!

Questions ?

Contact: Joakim Hedegård, Swerim joakim.hedegard@swerim.se

